



Euclidian Distance Method for Optimizing Linearly Chirped Fiber Bragg Grating Apodization Profile

Ahmad Fauzi Abas*, Yosef Taher Aladadi and Mohammed Thamer Alresheedi

Abstract

In this paper, we use Euclidian distance method to solve the tradeoff between Group delay Ripple (GDR) and Full Width Half Maximum (FWHM) Bandwidth. This method determines the optimum point by maximizing FWHM spectral bandwidth and minimizing GDR based on the value of sharpness parameters α and β . Three different apodization profiles were used to evaluate this method. The study shows that the best α and β is 16 and 2.25 respectively. The apodization profile that was optimized the most by this method is Tanh.

Keywords

Euclidean distance method; Optimization; Apodization profile; Linearly chirped apodized fiber Bragg gratings; Dispersion; Compensation

Introduction

Chromatic dispersion (CD) issues are very important to be dealt with in today high speed optical fiber transmission system, either in conventional S-, C-, and L-band, or the future 2000 nm long-band [1-7]. CD occurs because different wavelength components of the carrier signal propagate with different velocities [8]. One of the solutions to combat chromatic dispersion is by using apodized chirped fiber Bragg grating (CFBG) based Chromatic Dispersion Compensator (CDC). This technique is very efficient and practical. It maintains all-fiber network concept and at the same time operates at much lower insertion loss than the conventional Dispersion Compensating Fiber (DCF). CD compensation needs for large bandwidth; however, the bandwidth of CFBG is limited. It depends on the suppression of ripple in the profile, which is achieved at the cost of operating bandwidth. As a result, optimum performance cannot be achieved. Until today, several optimization techniques have been tested namely apodization window roll-off rate, asymptotic side lobe (SL) decay level, number of SLs, and average SL level (SL_{av}) [9]. Discrete inverse scattering algorithm (DISA) was used to obtain the optimized long period gratings (LPG) apodization profiles [10].

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This work is the continuation of work done by Aladadi et al. [11,12]. An optimized apodization profile was formulated by solving the coupled mode equation of CDC structure. Subsequent work was presented by Aladadi et al. [11] where three apodization profiles were evaluated to find the best profiles to be used in developing the CDC. In this paper, Euclidean distance method is used to optimize the apodization profile. This method maximizes the Full Wave Half Maximum (FWHM) spectral bandwidth (BW) and minimizes the group delay ripple (GDR). Three different apodization profiles were used in evaluating this optimization method.

Apodization Profile

Three different apodization profiles were used in this work, namely Tanh, Exponential and Hamming. Figure 1 shows the effect of apodization process to the FWHM spectral BW and GDR. From the Figure 1, it is obvious that when the GDR is eliminated, the signal experiences huge BW loss, which is referred as BW filtering effect. This is a serious issue due to unoptimized apodization profile. This issue is very important to be solved because the signal distortion that is caused by the BW filtering effect will result in bits errors, and shortens the maximum achievable transmission distance.

In this work, the following apodization profiles were used.

Tanh apodization profile,

$$\bar{\delta}_{neff} = \begin{cases} \left[\frac{\tanh\left[2\alpha\frac{z}{L_g}\right]}{\tanh(\alpha)} \right]^\beta & 0 \leq z \leq \frac{L_g}{2} \\ \left[\frac{\tanh\left[2\alpha\frac{L_g-z}{L_g}\right]}{\tanh(\alpha)} \right]^\beta & \frac{L_g}{2} \leq z \leq L_g \end{cases} \quad (1)$$

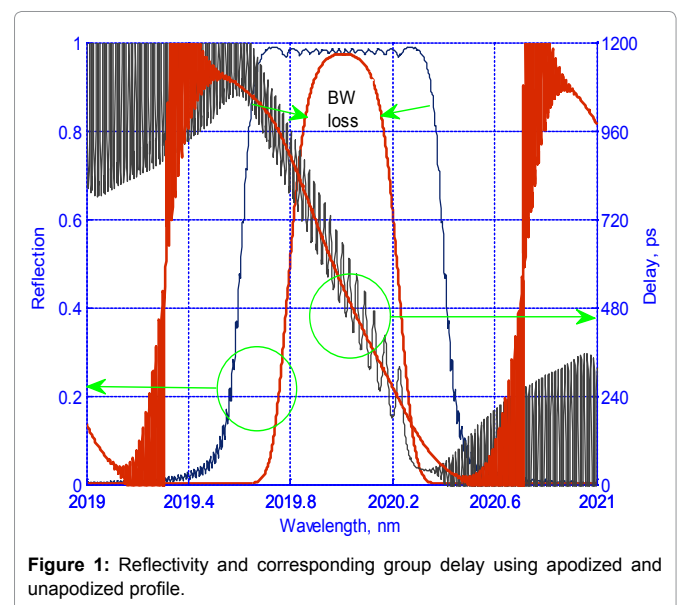


Figure 1: Reflectivity and corresponding group delay using apodized and unapodized profile.

Exponential apodization profile,

$$\bar{\delta}_{neff} = \left[\exp \left[-\alpha \left(\frac{z - \frac{L_g}{2}}{L_g} \right)^\beta \right] \right] \quad 0 \leq z \leq L_g \quad (2)$$

Hamming apodization profile,

$$\bar{\delta}_{neff} = \left[\frac{1 + \alpha \cos \pi \left[\frac{2z - L_g}{L_g} \right]}{1 + \alpha} \right] \quad 0 \leq z \leq L_g \quad (3)$$

Where $\bar{\delta}_{neff}$ is the refractive index change. α and β are the sharpness parameters that were used to control the shape of the reflectivity spectra and group delay ripple, and L_g is the grating length. The role of α and β on the apodization profiles is to control the profile sharpness. This role can be seen in Figures 2-4 which evaluate the value of $\bar{\delta}_{neff}$ against the normalized grating length with several values of α and β . In the previous studies, the best value of α and β has never been reported, which shows the importance of our work.

From Figure 2 (Tanh), we noticed that for different combination of α and β , the normalized grating length that produces maximum performance is different. For example, when $\alpha=2$ and $\beta=5$, the maximum performance can be achieved at $z/L_g=0.5$. However, when $\alpha=5$ and $\beta=1$, the maximum performance can be achieved not only at one value of z/L_g , but from $z/L_g=0.35$ to $z/L_g=0.65$. This can give us more flexibility in the design as we know that we have a range of grating length that can be used.

Similar characteristic can be observed for Exponential (Figure 3) and Hamming (Figure 4) apodization profiles. Between the three apodization profiles, the response differs. For example, the range of z/L_g that produces maximum performance for Exponential and Hamming is smaller in comparison to Tanh.

Euclidian Distance Method

Euclidean distance method analyses the normalized GDR

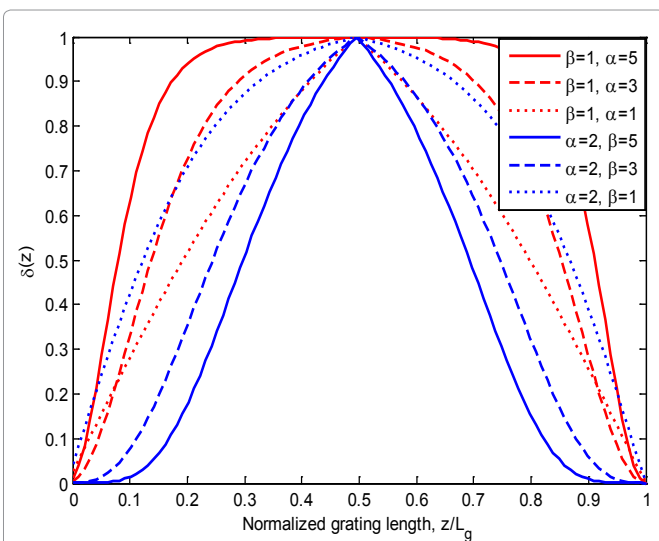


Figure 2: Tanh apodization profile with different sharpness parameters.

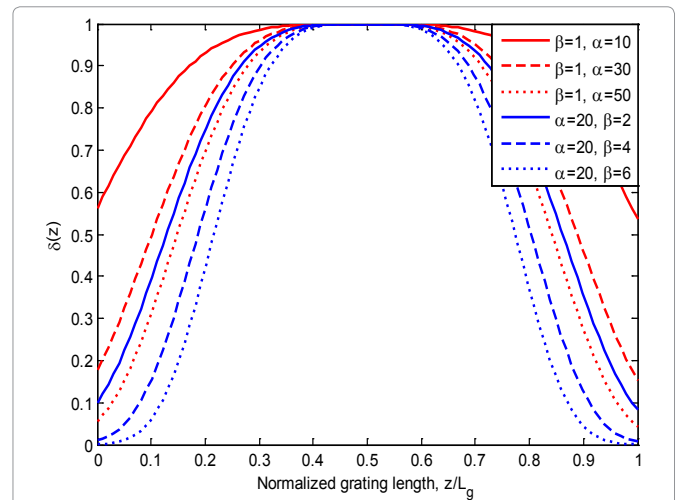


Figure 3: Exponential apodization profile with different sharpness parameters.

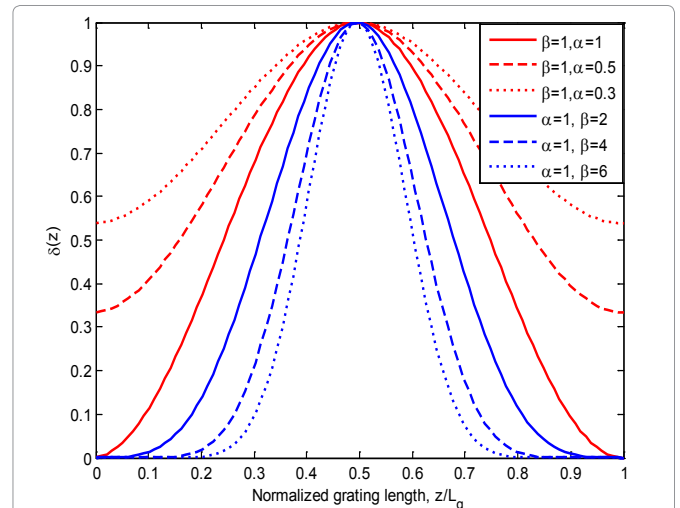


Figure 4: Hamming apodization profile with different sharpness parameters.

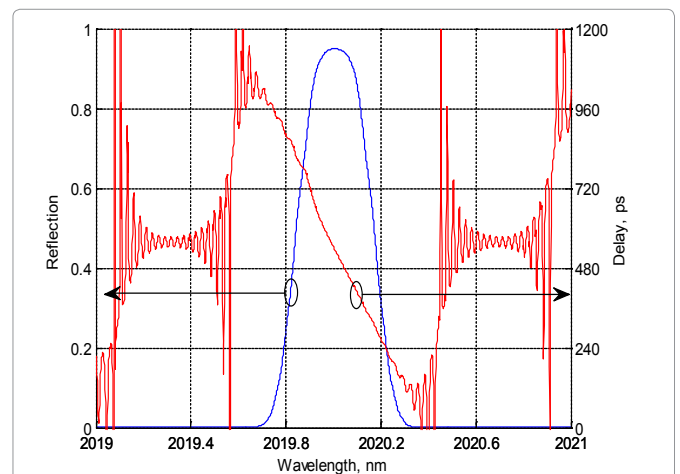


Figure 5: Reflectivity and corresponding group delay for Tanh apodization profile in case $\alpha=1$ and $\beta=2.25$.

and normalized FWHM spectral BW as shown in Equation 4 and Equation 5 [11,12].

$$F_{ripple} = \frac{A_{apod}(\alpha, \beta)}{A_{unapod}} \quad (4)$$

$$F_{BW} = \frac{BW_{apod}(\alpha, \beta)}{BW_{unapod}} \quad (5)$$

Where A_{apod} and A_{unapod} represent the amplitude of apodized and unapodized group delay ripple. BW_{apod} and BW_{unapod} represent the FWHM spectral BW of apodized and unapodized reflectivity spectrum.

From the relationship between F_{ripple} and F_{BW} , the Euclidian distance is derived, which is shown in Equation 6.

$$d(\alpha, \beta) = \sqrt{F_{ripple}(\alpha, \beta)^2 + (1 - F_{BW}(\alpha, \beta))^2} \quad (6)$$

To visualize the effect of α and β to the GDR and FWHM BW, the corresponding reflectivity and group delay at three different values of α were plotted with $\beta=2.25$. Figures 5-7 show the reflectivity and corresponding GDR for Tanh apodization profile at $\alpha=1, 40$ and 16 respectively. Figure 5 shows when $\alpha=1$, GDR is minimized but at the same time the FWHM BW is very narrow. In contrast, when large value of α was used huge GDR can be witnessed but with large FWHM

BW. Based on these observations, it can be understood that trade-off between GDR and FWHM BW needs to be formulated. In Figure 7, the partially optimized apodization profile is shown when both GDR and FWHM BW are at tolerated values.

Based on Equation (6), the optimum point of α is obtained at the minimum value of d , denoted as d_{min} . Figures 8-10 show the values of d at different value of α and β for different apodization profile.

The values of d_{min} for Tanh, Exponential and Hamming profiles are 0.123, 0.283 and 0.257 respectively. These results are recorded at $\alpha=16$ and $\beta=2.25$ for Tanh, $\alpha=66.67$ and $\beta=0.5$ for Exponential, and $\alpha=1$ and $\beta=0.333$ for Hamming profile.

The Euclidean distance was measured as follows. First, we fix β to 2.25, 0.5 and 0.333 for Tanh, Exponential and Hamming respectively. Next, by varying α , we plotted F_{ripple} against F_{BW} .

Figure 11 shows the relationship between F_{BW} and F_{ripple} for Tanh, Exponential and Hamming where the distance from the right bottom corner ($F_{BW}=1, F_{ripple}=0$) to any point in the curve is the Euclidean distance. From the Figure 11, it can be seen that the

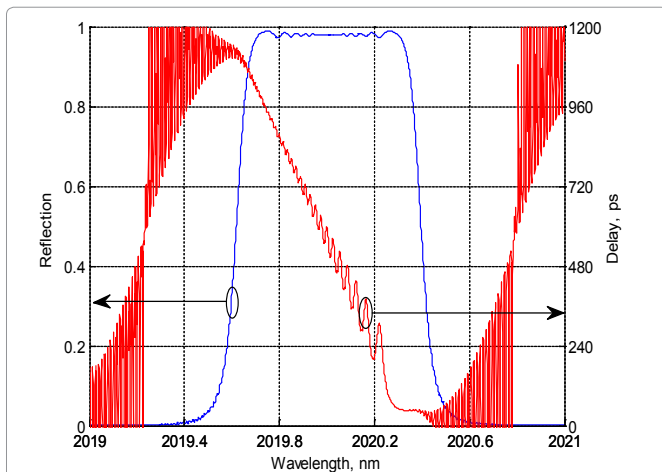


Figure 6: Reflectivity and corresponding group delay for Tanh apodization profile in case $\alpha=40$ and $\beta=2.25$.

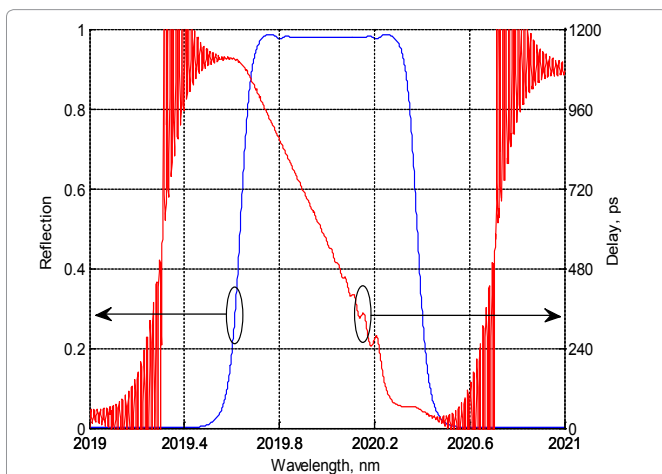


Figure 7: Reflectivity and corresponding group delay for tanh apodization profile in case $\alpha=16$ and $\beta=2.25$.

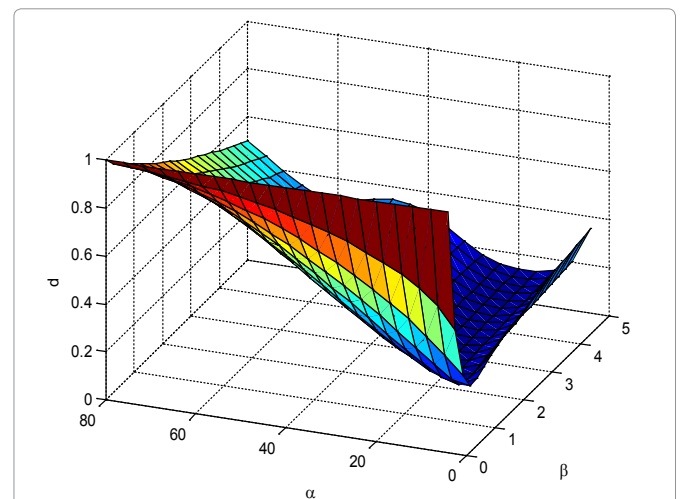


Figure 8: Euclidian distance, d , versus sharpness parameter, α , for tanh apodization profile.

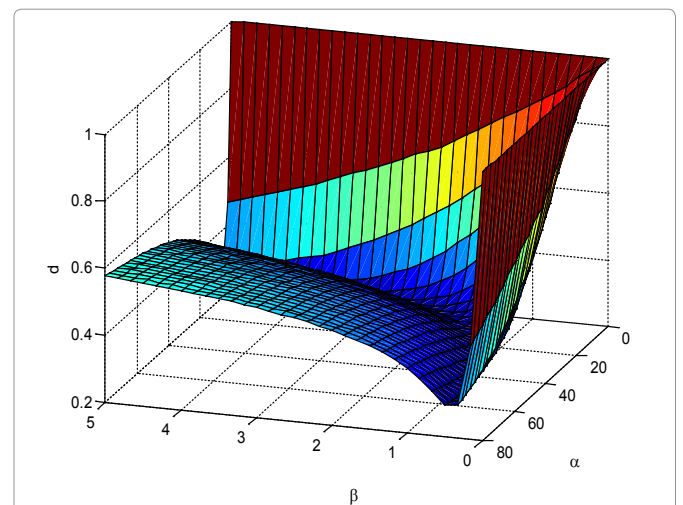


Figure 9: Euclidian distance, d , versus sharpness parameter, α , for exponential apodization profile.

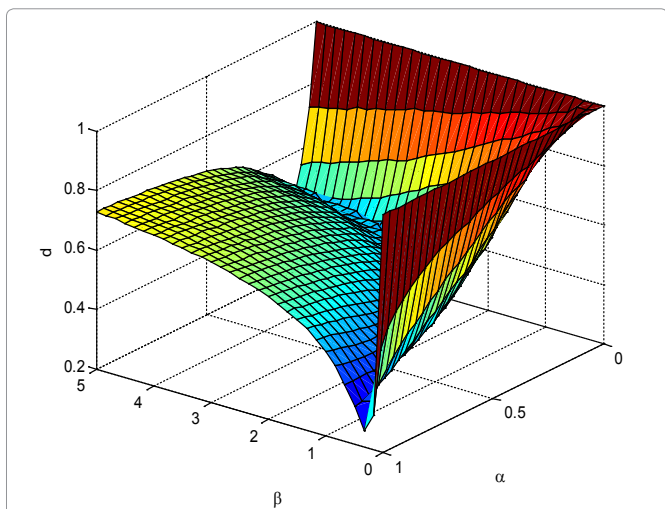


Figure 10: Euclidian distance, d versus sharpness parameter, α for hamming apodization profile.

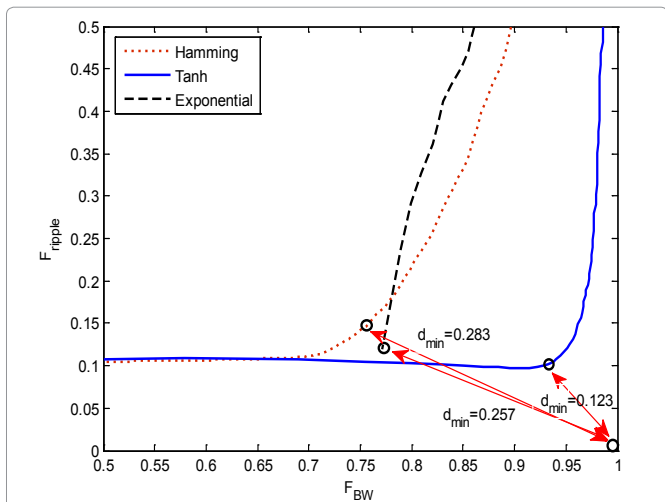


Figure 11: F_{ripple} versus F_{BW} , where the minimum Euclidian distance for Tanh, Exponential and Hamming is shown.

minimum Euclidian distance is at $F_{\text{BW}}=0.937$ and $F_{\text{ripple}}=0.105$ for Tanh, $F_{\text{BW}}=0.768$ and $F_{\text{ripple}}=0.163$ for Exponential, and $F_{\text{B}}=0.771$ and $F_{\text{ripple}}=0.119$ for Hamming apodization profile. From the results, it is clear that the best apodization profile is Tanh, while the best α and β is 16 and 2.25 respectively.

Conclusions

The optimization of apodization profile using Minimum Euclidean Distance method was formulated and tested. This method allows for accurate optimization of GDR and FWHM BW of the CDC. Our results also show that among the tested apodization profiles, Tanh was optimized the most by this new technique. The output of this paper is very important to the CD research and industry as it highlights an alternative solution to simplify the optimization process of CFBG-based CD Compensator.

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