



Research Article

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Gravity Data Transformation by Polynomial Fitting and Kriging Data Analysis of the Mamfe Basin (Cameroon)

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Abstract

Thirty-six gravity Bouguer data were collected in the Mamfe sedimentary basin. Third-order polynomial filtering was applied to the data. Third-order regional and residual gravity data were plotted as boxplots to compare distributions of different gravity fields. Boxplots enable to observe outliers in the data. These values allowed for a more detailed study of the observed regional and residual anomaly values as they could have a significant impact on the results. Boxplots also found that the gravity data showed asymmetry. The kriging analysis procedure was initiated to describe the spatial variability of the different gravity data. The Gaussian theoretical model was used to test anisotropy. The anisotropy test has shown that regional and residual gravity data exhibit geometric anisotropy and that spatial continuity is not necessarily the same in all directions. The unidirectional interpolated variograms were fitted with a tolerance of between 4° and 71° and a direction between -52° and 159°. 3D wireframe maps were created to map gravity fields in three-dimensional form and evaluate interpolated surfaces.

Keywords

Mamfe basin; Polynomial fitting; Boxplot analysis; Kriging analysis

Introduction

Geostatistics includes a number of methods and techniques for analyzing the spatial variability of spatially distributed or spatially structured variables [1]. The techniques developed by Krige et al. [2] and Matheron et al. [3] to evaluate mineralized bodies have been disseminated in many fields using spatial data. These various disciplines include petroleum geology [4], hydrogeology Hatvan et al. [5], hydrology Kovács et al. [6], meteorology Kohán et al. [7], oceanography Monestiez et al. [8], geochemistry Kern et al. [9], metallurgy Deutsch et al. [10], geography Herzfeld et al. [11], Hatvani et al. [12], environmental control Kint et al. [13], landscape ecology Webster et al. [14], soil science, and agriculture Fortin et al. [15] and Zhao et al. [16]. In the petroleum industries, geostatistics is successfully applied to characterize oil reservoirs on the basis of interpretations from sparsely localized data such as reservoir thickness, porosity, permeability, seismic data, gravity field or magnetic field data [17-20]. One of the most used geostatistical techniques for interpolation of spatial data is the kriging technique. Kriging is a complex interpolation

method and is considered as a method of estimating a regionalised variable at selected grid points. It can predict unbiased interpolation values with minimal variance [20,21].

In any kriging analysis, there are several main steps. These steps consist of creating an experimental semi-variogram, linking a theoretical model to the experimental semi-variogram and using the latter's information to perform kriging. More generally, this may be Determine appropriate theoretical models of semi-variogram; check the possibility of anisotropy of the experimental semi-variogram; generate kriging estimates and estimation errors, i.e., Kriging errors, for a point, area or volume; mapping the spatial distributions of kriging estimates and kriging errors. In a kriging analysis, all these components must be systematically taken into account [22-27]. What we can notice is that the analysis of spatial continuity or roughness of geospatial data in different directions and tolerances takes time [28-31].

The aims of this study are: to carry out the polynomial filtering of the Bouguer data of the mamfe basin, to plot the boxplots to understand the influence of the outliers in the data and to compare the distributions of the Bouguer gravity fields, regional and residual then to realize a kriging analysis of gravity data of the basin and their cartographies.

Location of the Study Area

The Mamfe sedimentary basin (Figure 1) is an intracratonic rift basin formed in response to the dislocation of the Gondwana supercontinent and following the separation of South American and African plates. The basin is a small extension of the Benue sedimentary basin. The basin is favorable to the exploration and exploitation of salt springs, minerals, precious stones and hydrocarbons. It has an area of approximately 2400 km² and is located between latitudes 5°30'N and 6°00'N and longitudes 8°40' E and 9°50' E (Figure 1). It has the form of a plain with an average altitude that varies between 90 and 300 m above the sea level.

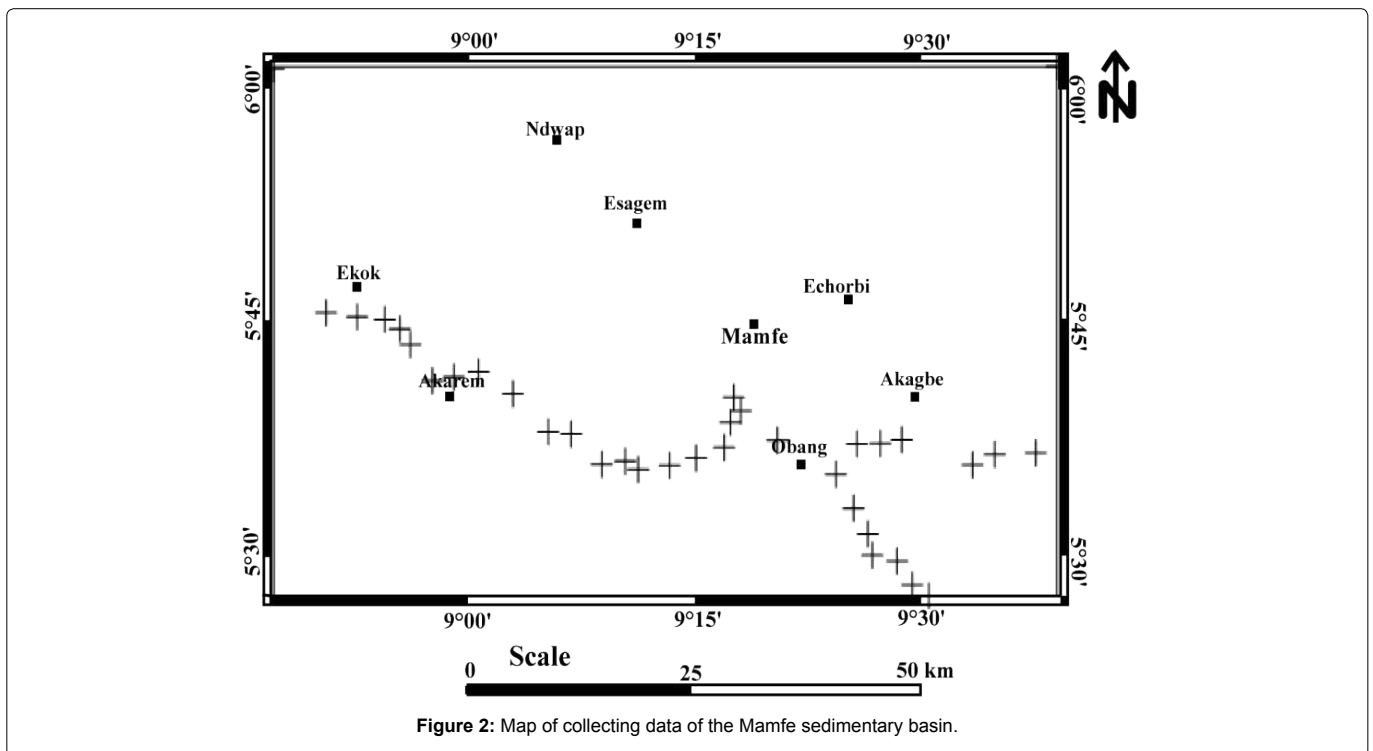
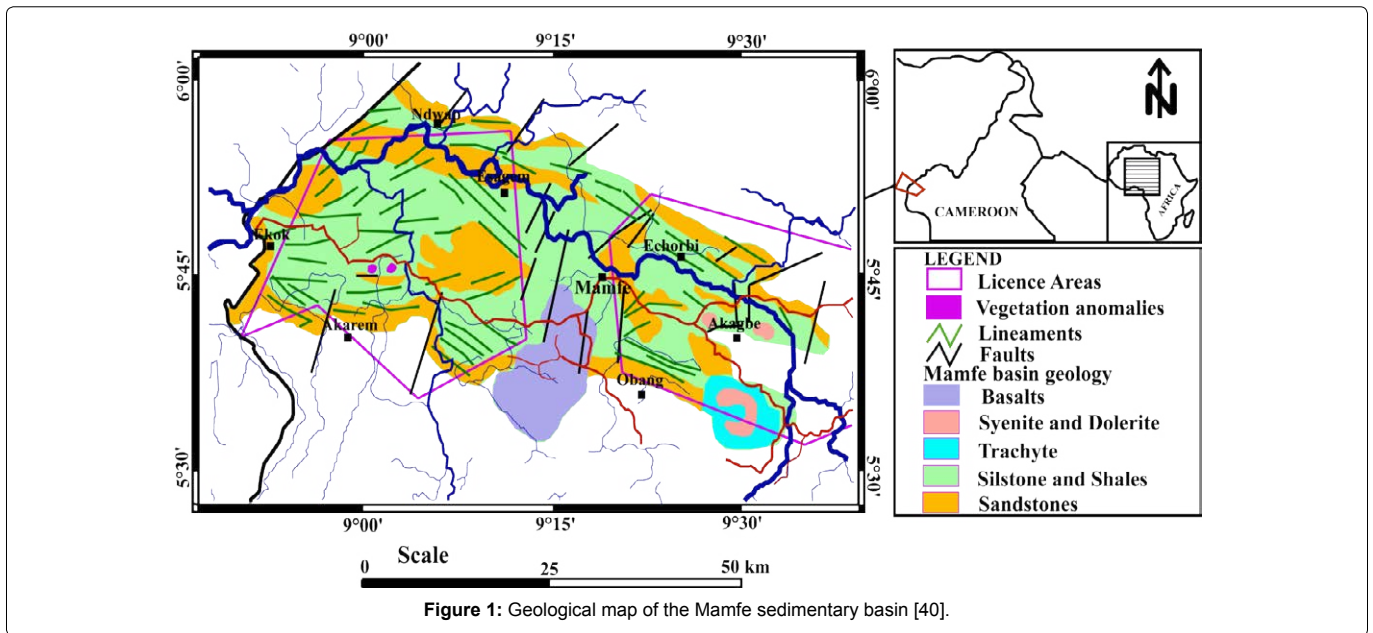
Figure 1 shows the available geological map of the basin. Some geological details were extrapolated or removed. The geological map is preliminary and has jointly been updated following several studies [32-41]. The geomorphology of the area is characterized by a succession of horst and grabens. Overall, the Mamfe sedimentary basin has a NW-SE structural trend with a length of 130 Km and a width of approximately 60 km. It is bordered by faults, lineaments and rivers such as Manyu, Munaya and extends from Cameroon to Nigeria [32-41].

Data Acquisition and Processing

Figure 2 shows the distribution of gravity data collected through the Mamfe Basin. It is deduced from the Cameroon gravity database that manages the RID (Research Institute for Development). The Lacoste-Romberg gravimeter (1975-1976) was used for data recording. The determination of the altitudes was made by barometric leveling with a Wallace-Tiernan altimeter. The RID gravity network established in Douala served as a reference base for measurements. The spatial reference coordinate system used is WGS84 and the data projection system is UTM.

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The Bouguer anomaly was calculated at each station using the expression by Poudjom et al. [42]: $B = G - (G_0 - C_z - T)$ Where G is the observed value of the gravitational field and its expression is: $G = G_r + \Delta G$ with G_r the value of the gravity field in a adopted station as reference and ΔG measuring the gravity field difference between the reference station and a given station. G_0 is the theoretical value of the gravitational field at the point of the reference ellipsoid corresponding to the station. G_0 has been defined in the IGSN71 reference system whose formula is:

$$G_0 = 978031.8 (1 + 0.053024 \sin^2 \phi - 0.0000022 \sin^2 \phi^2)$$

The error on the latitude of a station is considered between 0.2 mgal and 0.5 mgal with $\phi = 3^\circ$.

- C_z is the Bouguer correction
- It represents the sum of the correction of the free air $C_1(mgal) = 0.3086 Z$ and the plateau correction $C_2(mgal) = -0.0419dZ$ Where d is the density of the crust and Z the altitude of the station expressed in meters. For the reasons of homogeneity we adopted $d = 2.67$ for all the stations from where $C_z(mgal) = 0.1967Z$. The imprecision of the barometric leveling has led to an error on C_z generally less than 1 mgal

but which has reached 2 or 3 mgal in unfavorable cases.

- T: relief correction. It takes into account the relief around the station. The anomaly value at each point was tainted with a maximum error of 5 mgal in the worst conditions, in most cases the error remained below 3 mgal.

Materials and Methods

In linear geostatistics the choice of software and an interpolation method are very important for spatially analyzing a variable of interest [1-4]. We used R software Ihaka et al. [43] and Surfer Golden Software [44]. Surfer is a 2D and 3D surface mapping program that transforms random data into contours of continuous curved faces. Surfer uses twelve different methods to interpolate data; R is statistical software created by Ihaka et al. [43]. It is both a computer language and a work environment: the commands are executed by means of instructions coded in a relatively simple language, the results are displayed in text form and the graphics are displayed directly in a window of their own. This software is used for manipulating data, graphing and statistical analysis of this data.

In this part, we expose the polynomial fitting method and the different steps of the kriging method in the univariated framework.

The polynomial separation method

The polynomial separation method was used to produce the third degree regional and residual maps. The algorithm by Gupta and Murthy et al. [45,46] was used to adjust the polynomial surfaces to the Bouguer anomaly map. This method is based on the analytical least square method and the polynomial decomposition series.

The least-square method is used to compute the mathematical surface which gave the best fits to the gravity field within specific limits [45-47]. This surface is considered to be the regional gravity anomaly. The residual is obtained by subtracting the regional field from the observed gravity field. In practice, the regional surface is considered as a two-dimensional polynomial. The order of this polynomial depends on the complexity of the geology in the study area. The third-order polynomial surfaces of the regional anomaly obtained in this work is presented and the corresponding residual anomaly.

Mathematic formulation of the method

The Bouguer anomaly $B(x, y)$ in the given point $M(x, y)$ of the earth in Cartesian coordinates is governed by the relation:

$$B(x_p, y_p) = A(x_p, y_p) + R(x_p, y_p) \quad (1)$$

$B(x_p, y_p)$ is the sum of the residual anomaly $A(x_p, y_p)$ and the regional anomaly $R(x_p, y_p)$.

The surface $F(x_p, y_p)$ which is adapted to the gravity field data $g(x, y)$ is given by the following relation [45-49]:

$$F(x_i, y_i) = C_1 + C_2 X_i + C_3 Y_i + C_4 X_i^2 + C_5 X_i Y_i + C_6 Y_i^2 + \dots + C_{M-N} Y_i X_i^{N-1} + C_{M-N-1} Y_i X_i^{N-1} + \dots + C_M Y_i^N \quad (2)$$

Where N is the order of the polynomial, $M = \frac{(N+1)(N+2)}{2}$ the number of terms of the polynomial, and C_M the coefficients to be determined:

The first order Polynomial is:

$$F(x_p, y_p) = C_1 + C_2 X_i + C_3 Y_i \quad (3)$$

The second order polynomial is:

$$F(x_i, y_i) = C_1 + C_2 X_i + C_3 Y_i + C_4 X_i^2 + C_5 X_i Y_i + C_6 Y_i^2 \quad (4)$$

The third order polynomial is:

$$F(x_i, y_i) = C_1 + C_2 X_i + C_3 Y_i + C_4 X_i^2 + C_5 X_i Y_i + C_6 Y_i^2 + C_7 X_i^3 + C_8 Y_i X_i^2 + C_9 X_i Y_i^2 + C_{10} Y_i^3 \quad (5)$$

We denote by $\varepsilon_i = B(x_p, y_p) - F(x_p, y_p)$ the difference between the homologous points of the experimental and analytical surfaces respectively and by N_0 the number of stations P_i in which the Bouguer anomaly is known. The adjustment of the surfaces which consists in making the quadratic deviation minimal is expressed by:

$$E = \sum_{i=1}^{N_0} \varepsilon_i^2 \text{ then } \frac{\partial E}{\partial C_k} = 0 \text{ with } 1 \leq k \leq \frac{(N+1)(N+2)}{2} \quad (6)$$

$$E = \sum_{i=1}^{N_0} [B(x_i, y_i) - F(x_i, y_i)]^2 \text{ and } \frac{\partial E}{\partial C_k} = 0$$

We then obtain a system of (M) equations with (M) unknowns. The unknowns are the coefficients C_k of the polynomial $F(x_p, y_p)$ of order N . Once the coefficients are determined we determine the analytic regional anomaly $R(x_p, y_p) = F(x_p, y_p)$ and the residual by:

$$A(x_p, y_p) = B(x_p, y_p) - F(x_p, y_p) \quad (7)$$

The polynomial method is particularly used when the amplitude of the residual anomalies is negligible compared to the regional one. Apart from the polynomial method there are other methods such as the upward continuation method.

Variographic formalism and kriging

In a classical framework, kriging analysis generally involves two stages: the variogram estimation and the use of the model coefficients for Kriging [17-20].

The formalism of variographic estimation: The variogram is the basic tool in kriging analysis and is required for geostatistical spatial prediction. The variogram is estimated by the experimental variogram $\gamma(h)$, which is calculated from the discrete data as follows [17-20]:

$$\gamma^*(h) = \frac{1}{2N} \sum_{i=1}^N [Z(x_i) - Z(x_i + h)]^2$$

where N is the number of pairs of points distant from h .

Once the experimental variogram has been calculated, it is necessary to replace it with a theoretical variogram whose coefficients are estimated by a least squares procedure [20].

There are several types of theoretical variogram models used for kriging [17-20]:

The spherical variogram is characterized by :

$$\begin{cases} \gamma(h) = C \left[1.5 \left(\frac{h}{a} \right) - 0.5 \left(\frac{h}{a} \right)^3 \right] & \text{si } 0 < h < a \\ \gamma(h) = C & \text{si } h \geq a \end{cases}$$

With a the range, h the interpolation step and C the constant sill

The Gaussian variogram is characterized by:

$$\gamma(h) = C \left[1 - \exp \left[-3 \left(\frac{h}{a} \right)^2 \right] \right]$$

The exponential variogram is characterized by:

$$\gamma(h) = C \left[1 - \exp \left[-\frac{3h}{a} \right] \right]$$

The power variogram is characterized by:

$$\gamma(h) = Ch^b \quad 0 < h < 2$$

For $b = 1$, the variogram is linear; $b = 2$, the variogram is a parabola

The formalism of variographic anisotropy: There are different types of anisotropies which enable to know the different orientations that spatialized data can take [17-20]. Geometric anisotropy is the simplest case. A geometric anisotropy is reflected in the experimental variograms by a range which varies according to the direction. Geometric anisotropy is observed when the variogram respects the following mathematical formulation:

$$\frac{(a_\theta \cos \theta)^2}{a_g^2} + \frac{(a_\theta \sin \theta)^2}{a_p^2} = 1$$

With a_g the maximum range, a_p the minimum range and a_θ the range in the anisotropy direction θ

Anisotropy is called zonal when it cannot be solved by a simple geometric or linear coordinate's transformation. It causes for the bearing variogram which varies according to the space direction.

The kriging formalism

Kriging is an interpolation method that gives the best unbiased linear estimate of the point value of a regionalised variable [2,3]. The kriging interest is that it enable to calculate the estimation error i.e the kriging variance [2,3]. It allows the taking into account of: the data configuration; the distance between data and targets; spatial correlations and external information. Kriging is an exact interpolator, it has a screen effect, it is almost without conditional bias. It is transitive, generally performs a smoothing and takes into account the field size to estimate and the position of the points between them [2,3].

The mathematic formulation of kriging imposes the minimization of the following variance [1-4]:

$$\sigma_e^2 = \text{Var}[Z_V - Z_V^*] = \text{Var}[Z_V] + \text{Var}[Z_V^*] - 2\text{Cov}[Z_V, Z_V^*]$$

Where Z_V represents the known values at different points and:

$$Z_V^* = \sum_{i=1}^N \lambda_i Z_i \text{ is the estimator}$$

λ_i is the weight and Z_i is the random variable corresponding to each point.

Since kriging is an unbiased interpolator then:

$$Z_V^* = \sum_{i=1}^N \lambda_i Z_i = 1$$

To minimize the kriging variance we use the Lagrangian [1-4]:

$$L(\lambda_i, \mu) = \sigma_e^2 + 2\mu \left[\sum_{i=1}^N \lambda_i - 1 \right]$$

$$L(\lambda_i, \mu) = \text{Var}[Z_V] + 2 \sum_{i=1}^N \lambda_i \sum_{j=1}^N \lambda_j \gamma[Z_i, Z_j] - 2 \sum_{i=1}^N \lambda_i \gamma[Z_V, Z_i] + 2\mu \left[\sum_{i=1}^N \lambda_i - 1 \right]$$

With μ the Lagrange multiplier

By calculating: $\frac{\partial L(\lambda_i, \mu)}{\partial \lambda_i} = 0$ and $\frac{\partial L(\lambda_i, \mu)}{\partial \mu} = 0$ we obtain the system of equation:

$$\begin{cases} \sum_{j=1}^N \lambda_j \gamma[Z_i, Z_j] + \mu = \gamma[Z_i, Z_V] \quad \forall i = 1, 2, 3 \dots N \\ \sum_{i=1}^N \lambda_i = 1 \end{cases}$$

The variance of kriging is given by:

$$\sigma_K^2 = \sum \lambda_i \gamma(Z_i, Z_V) - \gamma(Z_V, Z_V) + \mu$$

In order to solve the system numerically, it is convenient to write it in matrix form $AX=B$ We obtain:

$$\begin{bmatrix} \sigma^2 & \gamma[Z_1, Z_2] & \dots & \gamma[Z_1, Z_N] & 1 \\ \gamma[Z_2, Z_1] & \sigma^2 & \dots & \gamma[Z_2, Z_N] & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \gamma[Z_N, Z_1] & \gamma[Z_N, Z_2] & \dots & \sigma^2 & 1 \\ 1 & 1 & 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_N \\ \mu \end{bmatrix} = \begin{bmatrix} \gamma[Z_1, Z_V] \\ \gamma[Z_2, Z_V] \\ \vdots \\ \gamma[Z_N, Z_V] \\ 1 \end{bmatrix}$$

The system allows finding the set of weights λ_i and the Lagrange multiplier μ that minimize the variance and make the estimator unbiased. The variance of kriging is then obtained by the following formula:

$$\sigma_K^2 = X^T B - \gamma(Z_V, Z_V) = \sigma^2 - \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_N \\ \mu \end{bmatrix} \begin{bmatrix} \gamma[Z_1, Z_V] \\ \gamma[Z_2, Z_V] \\ \vdots \\ \gamma[Z_N, Z_V] \\ 1 \end{bmatrix}$$

With the X^T transpose of $X=A^{-1}B$

The system of equations can also be expressed in terms of covariance under the assumption that the random process is stationary.

Results

In this part, we present the results of polynomial separation by boxplots, variographic analysis and data mapping.

Polynomial separation boxplots analysis

It is interesting to use box-plots when you want to visualize concepts such as the symmetry, the dispersion or the centrality of the values distribution associated with a variable. They are also very interesting for comparing variables based on similar scales. The graphs (Figure 3) represent Bouguer's gravity fields and interpolated regional and residual data. They show different shapes and positions of box-plots. These graphs enable to summarize the gravity data in a simple and visual way, to identify the extreme values and to understand the different anomaly values distribution.

It can be noted that overall 50% of gravity anomaly values are inside each box. The values outside the box plots are represented by dots. It cannot be considered that if an observed value is outside the box-plots then it is an outlier. However, this indicates that this observed value needs to be studied in more detail. Outliers are data values that are far removed from other data values and can have a significant impact on the results.

These boxes have variable widths, it is not a simple aesthetic transformation, and the width is proportional to the size of the

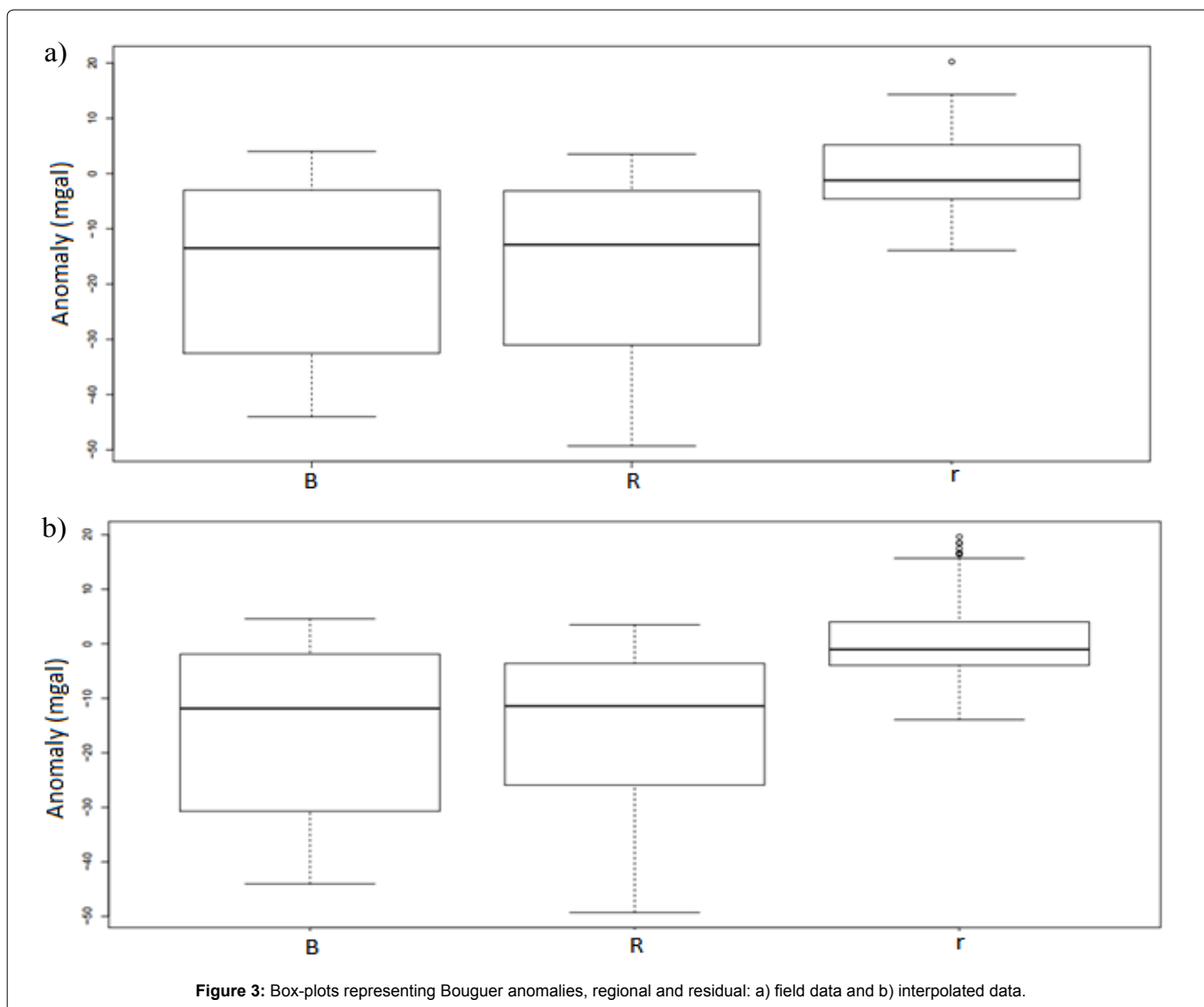


Figure 3: Box-plots representing Bouguer anomalies, regional and residual: a) field data and b) interpolated data.

anomaly values. The widths of the two parts of the box-plot reflect the dispersion of the values located at the center of the series (the box contains 50% (approximately) of all anomalies: 25% at the top of the median and 25% at the bottom); in general, the box-plots will be all the more extensive as the dispersion of the series of values is great.

The median is represented by the line in the box. The median is a common measure of data centering. Half of the values are lower or equal and half of the values are greater or equal.

When the data is asymmetrical, the majority of them are located on the upper or lower side of the graph. Asymmetry indicates that the data may not be normally distributed (Table 1).

Variographic analysis of the data

Variographic analysis plays a key role in the process of assessing the correlation level of spatialized data and their modeling. It indicates problems related to data dispersion and allows kriging or mapping in a particular area [17-20].

Anisotropy analysis of the field data

Figure 4 shows the variograms of all Bouguer gravity data, regional and residual. Each variogram is represented by the cloud, the experimental variogram and the three theoretical models selected for the anisotropy tests. The experimental variogram is a graph that shows the contributions of each pair of points to the final variogram. The scatter plot gives a visual impression of the dispersion of values at different offsets. He has no precise direction. We chose a direction and a tolerance each time to obtain an unidirectional variogram which enable to neglect the lag h.

Anisotropy is the parameter that allows us to better know the spatial continuity of the values of Bouguer, regional and residual gravity fields. Figure 4 shows the simulation of theoretical Gaussian variograms across the experimental variograms cloud. These figures prove that bouguer, regional and residual gravity data present a geometric anisotropy. Spatial continuity is not necessarily the same in all directions. The Gaussian model fit the dataset quite well (Table 2).

Table 1: Bouguer anomaly values as well as regional and residual anomalies obtained from polynomial separation.

Number	X (Longitudes)	Y (Latitudes)	Bouguer anomalies	Regional anomalies	Residual anomalies
1	9,636	5,691	-44	-4,7204	6,72024
2	9,592	5,687	-43	2,75236	1,24764
3	9,567	5,679	-42	3,18388	-1,18388
4	9,487	5,701	-39	3,51149	-3,51149
5	9,463	5,697	-36	3,25523	-5,25523
6	9,439	5,696	-32	3,31059	-5,31059
7	9,352	5,701	-20	-0,17256	-2,82744
8	9,313	5,727	-18	0,14928	-4,14927
9	9,3	5,716	-15	0,53131	-3,53131
10	9,304	5,739	-16	-1,55684	0,55684
11	9,294	5,694	-12	-5,82415	9,82415
12	9,415	5,671	-28	-6,51968	3,51968
13	9,436	5,641	-30	-10,72953	7,72953
14	9,451	5,617	-31	-10,98765	5,57853
15	9,456	5,598	-33	-12,57853	4,98765
16	9,483	5,592	-36	-13,15335	6,15335
17	9,5	5,571	-33	-13,37963	5,37963
18	9,517	5,562	-27	-13,15335	1,65255
19	9,263	5,685	-8	-11,47765	-3,52235
20	9,234	5,678	-7	-9,4475	-6,5525
21	9,201	5,674	-7	-11,03323	-6,96677
22	9,184	5,682	-6	-15,87953	-4,12047
23	9,159	5,679	-3	-23,30415	-4,69585
24	9,126	5,706	-3	-28,72188	-1,27812
25	9,062	5,742	-1	-33,31109	2,31109
26	9,023	5,761	-3	-36,71332	3,71332
27	8,997	5,756	-4	-39,55585	3,55585
28	8,974	5,753	-3	-44,39541	11,39541
29	8,949	5,784	-3	-47,23789	20,23789
30	8,938	5,799	-2	-22,00851	-9,99138
31	8,857	5,812	4	-23,66246	-1,27812
32	8,89	5,808	2	-25,08232	-13,91768
33	8,921	5,806	0	-34,16419	-7,83581
34	9,101	5,708	4	-35,62284	-7,37716
35	8,8	6,03	2	-39,54111	-4,45889
36	9,66	6,03	-35	-49,29324	14,29324

Variographic analysis of grid data

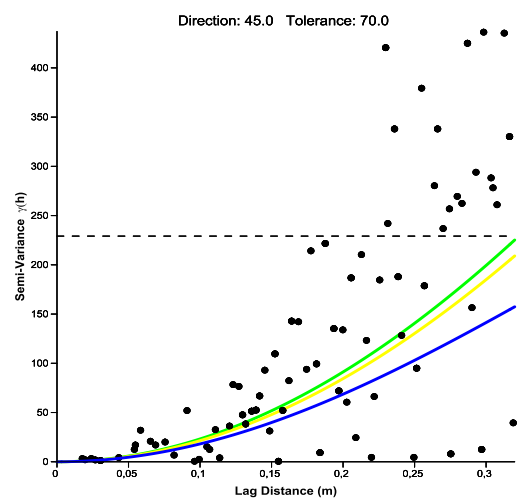
A variogram expresses the semi-variance of a regionalized variable and its variation as a function of the lag distance h . This variogram shows that, beyond a certain limit called range, no spatial correlation exists between the points. A theoretical variogram model is first computed to fit the experimental variogram obtained with the data, and is then used from Kriging [17-20].

The gridded data variograms are shown in Figure 5. The different experimental variograms clouds were fitted by the Gaussian theoretical variogram. The tolerances and directions chosen were a compromise between the need to have a sufficient number of pairs of points for calculating the variogram and the risk of too much smoothing of the curve. Overall the three variograms are unidirectional. The tolerance direction varies between 4° and 71° and the direction between -52°

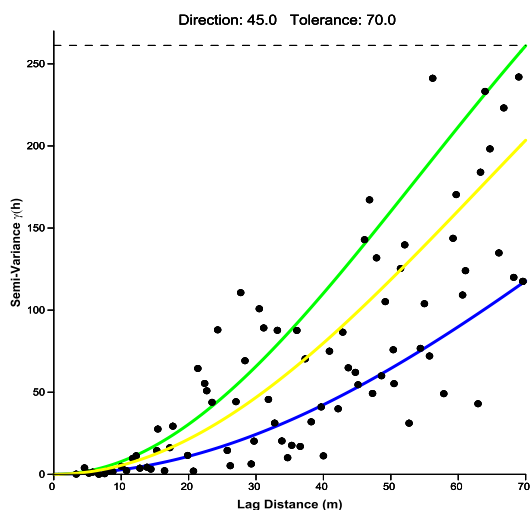
and 159° . These values were each time set so that the direction of any particular lag distance h , becomes unimportant (Table 3).

Interpretation of 3D wireframe maps

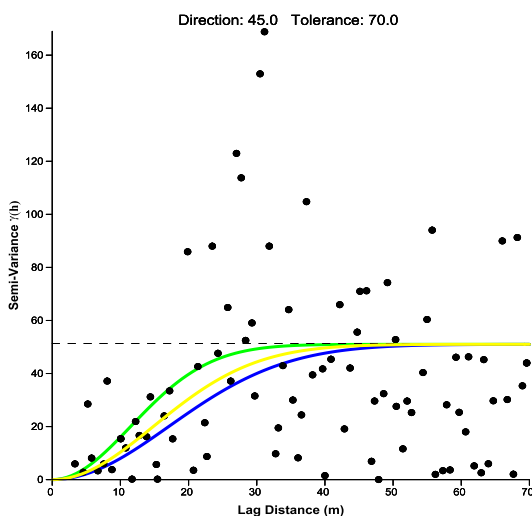
3D Wireframe map models are three-dimensional cartographic forms of the superficial and deep geological formations commonly used in geology and mining. The wireframe model maps a set of points with known triaxial Cartesian (x, y, z) coordinates. Before the plot, a grid routine is used to place the randomly located field data into a regular grid with selected spacing. The wireframe plot results in an open grid (x, y) with the anomaly of each grid node corresponding to the z coordinate at that point. The wireframe structures that we present in this part are three-dimensional representations of the gravity data of the Mamfe basin. These wireframe structures cannot be larger or smaller than the extent of the grid data file.



a) Simulation of the Bouguer data geometric anisotropy



b) Simulation of the regional data geometric anisotropy

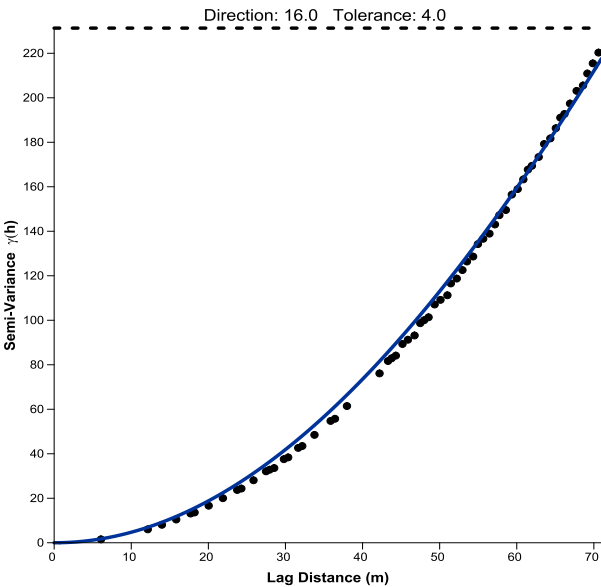


c) Simulation of the residual data geometric anisotropy

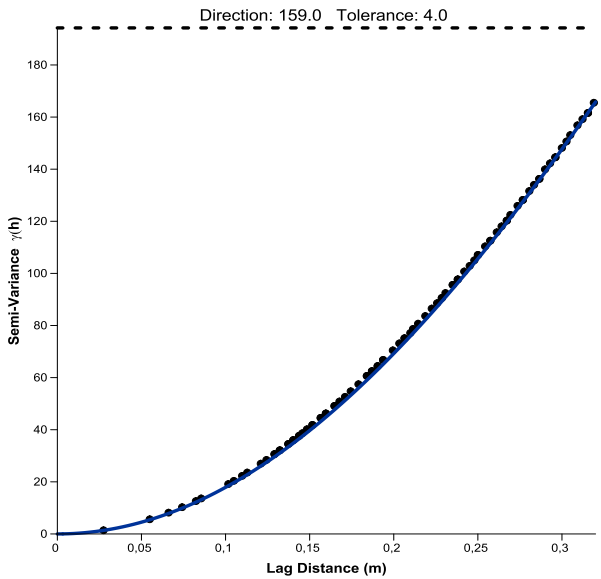
Figure 4: Simulation of the gravity data anisotropy.

Table 2: Characteristics of different models of anisotropy.

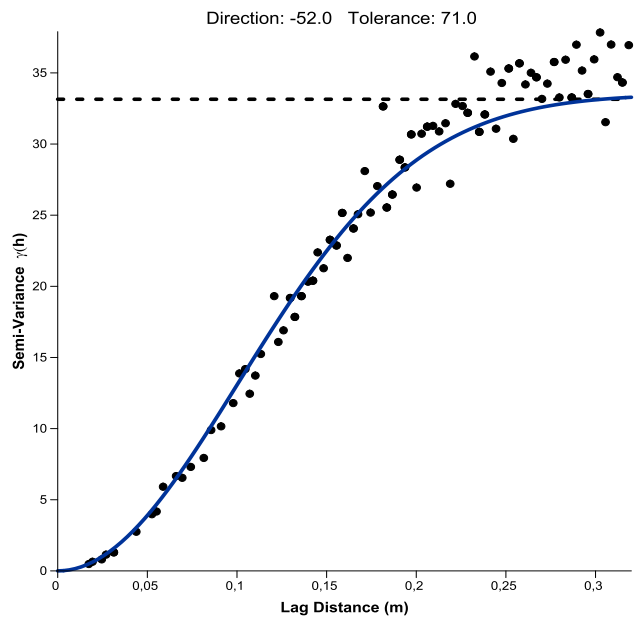
Bouguer Anomaly Data		
Models	Anisotropy angle	Anisotropy ratio
Gaussien 1 (green)	105	2
Gaussien 2 (yellow)	115	1.8
Gaussien 3 (blue)	140	2
Regional Anomaly Data		
Gaussien 1 (green)	140	1.54
Gaussien 2 (yellow)	100	1.4
Gaussien 3 (blue)	10	0.7
Residual Anomaly Data		
Gaussien 1 (green)	30	3.3
Gaussien 2 (yellow)	45	0.2
Gaussien 3 (blue)	15	0.1



a) Fitted variogram of Bouguer grid data



b) Fitted variogram of regional grid data



c) Fitted variogram of residual grid data

Figure 5: Fitted Variograms of gridded data (Experimental (line with markers) and theoretical semi-variogram (continuous line)).

Table 3: Characteristics of fitted experimental variogram.

Experimental variogram and Models	Max lag distance	Lag with	Vertical scale	Anisotropy ratio	Anisotropy Angle	Tolerance	Direction
Bouguer variogram	71	0.1775	231.3	2.3	100	4	16
Regional variogram	0.32	0.0008	194.2	2	70	4	159
Residual variogram	0.32	0.0008	37.9	2	162.8	71	-52

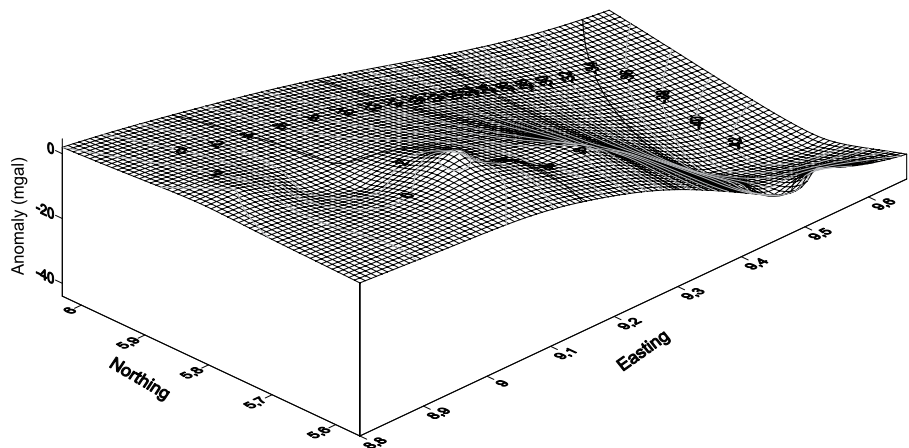


Figure 6: Bouguer 3D wireframe model with draped contours of the mamfe basin.

Bouguer 3D wireframemap

The Bouguer 3D wireframe map gives an idea of the structural distribution of the superficial and deep geological formations (Figure 6). It reflects the regular and continuous variations of the Bouguer gravity field of the Mamfe basin. The Bouguer 3D wireframe map indicates areas of existence of slopes and density discontinuities such as faults.

Regional 3D wireframe map

The Regional 3D wireframe map shows the overall gravity regional trends affecting the basement of the Mamfe Basin (Figure 7). These trends are N-S, E-W. This graph shows areas where the basement seems to have undergone a dilation confirming the hypothesis of magmatic upwelling in the basin; while the platform zone can be associated with a consolidation of the basement.

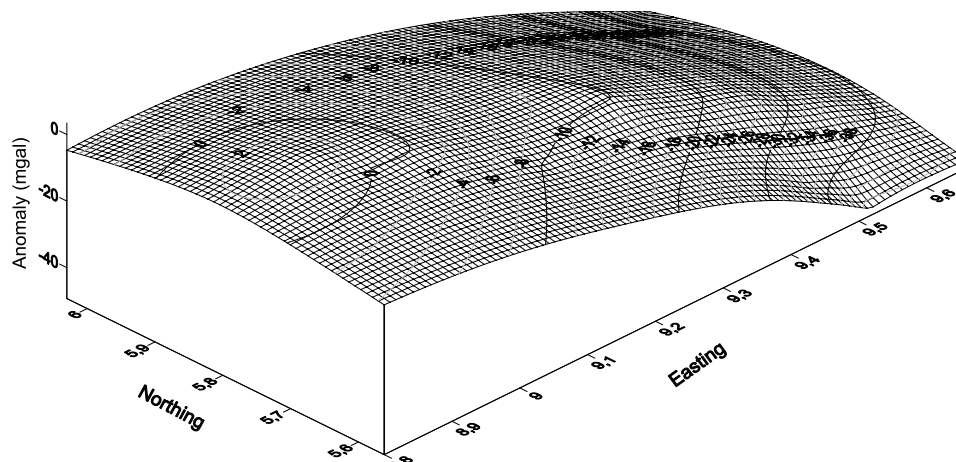


Figure 7: Regional 3D wireframe model with draped contours of the mamfe basin.

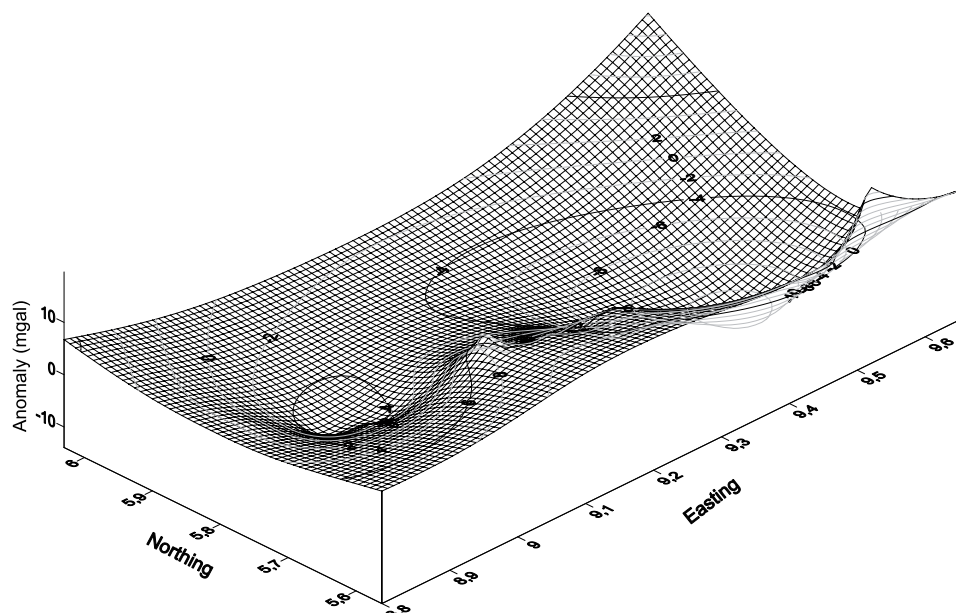


Figure 8: Residual 3D wireframe model with draped contours of the mamfe basin.

Residual 3D wireframemap

The Residual 3D wireframe map gives a three-dimensional representation of the sedimentary layer in the Mamfe basin (Figure 8). It is characterized by two negative gravity anomalies that can be associated with sedimentary infilling zones.

Conclusion

In this study, thirty six gravity Bouguer data were collected in the Mamfe sedimentary basin. Third-order polynomial filtering was applied to the data. Third-order regional and residual gravity data were obtained. The dataset was plotted as boxplots to understand the influence of the outliers in the data and then to compare Bouguer gravity field distributions, regional and residual. The kriging analysis procedure was initiated to: describe the spatial variability of the different gravity data; identify spatial correlations and different trends and directions of experimental semi-variograms; check the possibility

of the experimental semi-variograms anisotropy ; fit interpolated semi-variogram models using mathematical functions; Create the 3D wireframe maps of the different gravity fields from the new data grids to evaluate the interpolated surfaces.

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